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A Controller-in-the-Loop Simulation of Ground-Based Automated Separation Assurance in a NextGen Environment

Jeffrey Homola, Thomas Prevot, Joey Mercer,
Connie Brasil, Lynne Martin, & Christopher Cabrall
San Jose State University | NASA Ames Research Center

Acknowledgments



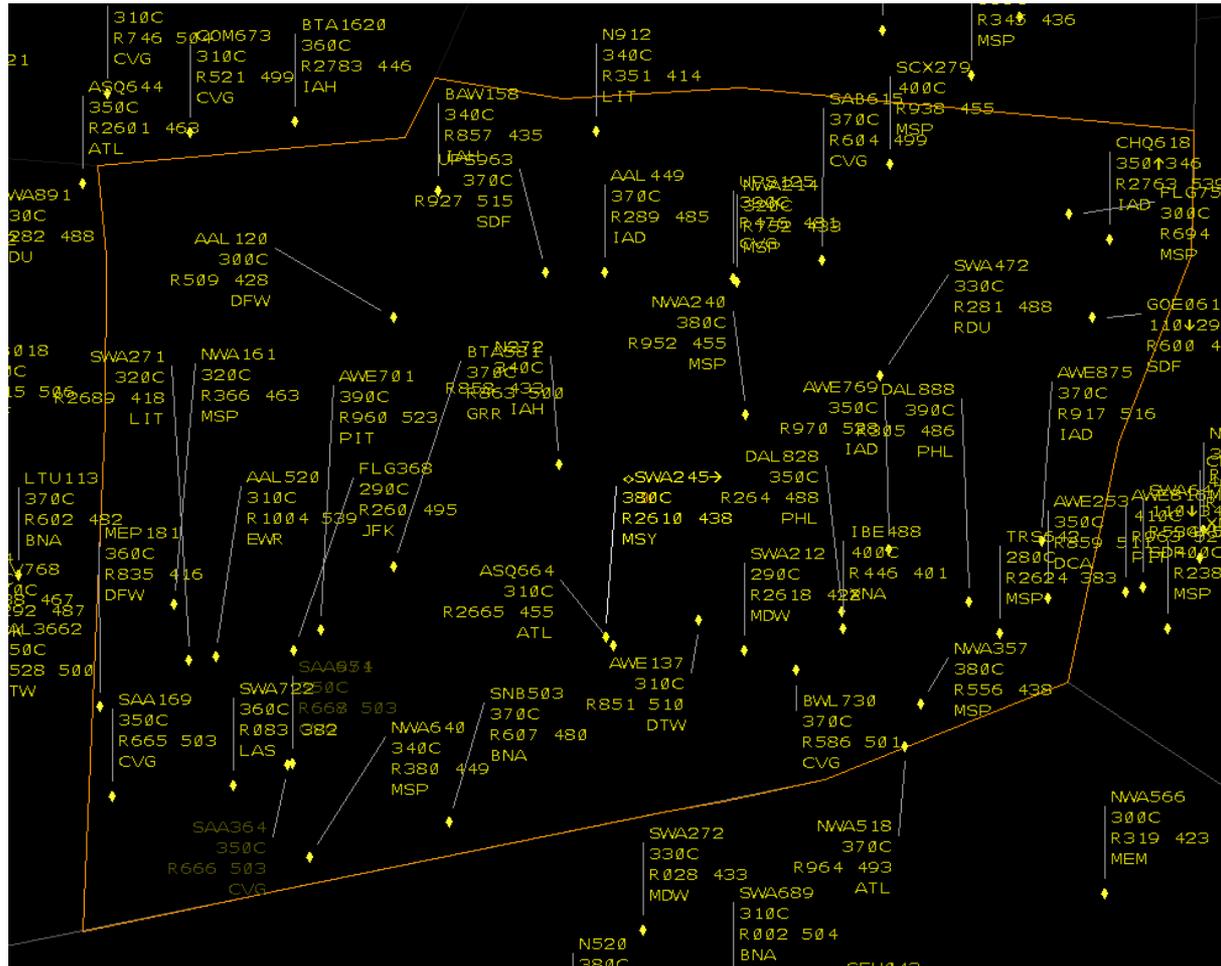
NASA Airspace Program

Federal Aviation Administration (FAA)

NASA Langley Research Center's Air Traffic
Operations Laboratory (ATOL) team



The Problem



- NextGen is expected to accommodate a **threefold (3X) increase** in air traffic demand compared to today's levels
- Cognitive resources of air traffic controllers are **limited**
- Conventional clearance-based separation assurance (SA) is **not possible** in the envisioned high density environment

Airspace Operations Laboratory



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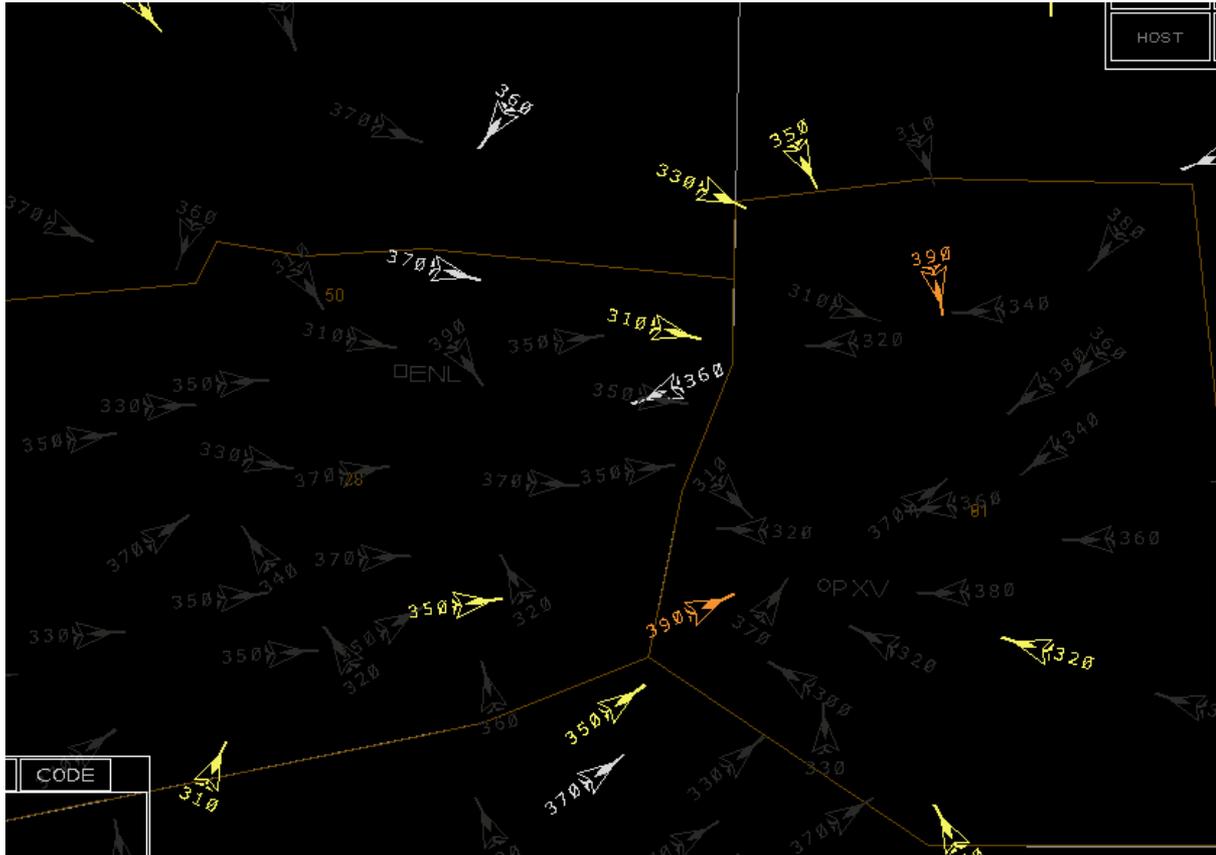
Beginning in 2007, a series of HITL simulations on ground-based automated SA have been conducted in the AOL



SA1 (2007)



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J. Homola, "Analysis of Human and Automated Conflict Resolution Capabilities at Varying Levels of Traffic Density". (Master's Thesis). San Jose State University, San Jose, California, 2008.

T. Prevot, J. Homola, and J. Mercer, "Human-in-the-Loop Evaluation of Ground-Based Automated Separation Assurance for NextGen". ICAS 2008-11.4.5, and AIAA-ATIO-2008-8885, Anchorage, Alaska, 2008.

- Tested SA at three progressive levels of traffic density: **1X, 2X, 3X**
- Varied levels of automated SA support across traffic levels: **Manual, Interactive, Fully Automated**
- Automation provided significant benefits in terms of safety and efficiency particularly at 2X and 3X. Significant reduction in workload. Resolutions provided by automation generally acceptable.

SA3 (2010) Background



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- NASA's FY2010 ARMD Annual Performance Goal: "Conduct simulations of automated separation assurance with sequencing, spacing, and scheduling constraints."
- JPDO concerns regarding the "lack of clarity" surrounding the functional allocation of new functions and responsibilities between the ground-based ATC and flight deck-based systems.

SA3 (2010)



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Two separate but collaborative studies on automated SA conducted from both the air- and ground-side perspectives in the ATOL and AOL

NextGen Separation Assurance Simulations

- A cross-center team accomplished a pair of companion human-in-the-loop simulation experiments designed to promote comparability of ground and airborne allocations of the separation function applied within the advanced NextGen construct of “four-dimensional trajectory-based operations.”
- In separate laboratories, the Langley simulation modeled a distributed airborne allocation of separation assurance using self-separation capability, and the Ames simulation modeled a centralized ground-based allocation using trajectory data link capability.
- Both concepts used Automatic Dependent Surveillance Broadcast for surveillance and computer automation to support conflict detection and resolution.
- Commercial transport pilots in the Langley simulation and professional air traffic controllers in the Ames simulation shared the same traffic scenarios.
- Results from these companion experiments and future coordinated research studies will help the FAA and industry make more informed decisions regarding NextGen design, technology development, and pilot and controller procedures.

NASA Langley's Air Traffic Operations Lab

NASA Ames' Airspace Operations Lab

NextGen Separation Assurance Simulations

Researchers observing experimental data collection in Langley's Air Traffic Operations Lab

Air Traffic Control room in Ames' Airspace Operations Lab

NextGen simulation workstation

Air traffic control workstation

Pre-scheduled check-out of self-separation functions by subject master expert (SME) pilots.

Research team uses ground-based separation assurance functions.

Poster created at NASA Langley for NASA Langley Center Team Award Ceremony on June 3rd 2010

D. Wing, T. Prevot, J. Murdoch, et al. “Comparison of Airborne and Ground-Based Functional Allocation Concepts for NextGen Using Human-In-The-Loop Simulations”. AIAA, 10th ATIO, 2010.

Overall Experiment Design

Short duration runs

Timing of Arrival Time changes	Basic (STA)	S1
	Dispersed (one every minute)	S2
	Synchronous (all at 6 or 8 minutes)	S3

Medium duration runs

Arrival Time Constraints	No (Baseline)	M1	M2
	Yes (STA)	M4	M3
		A	B
NextGen (Traffic) Level			

Exploratory Long duration runs

Level of Traffic with Arrival Time Constraints	Light	L1	L2
	Heavy	L3	L4
		Growing	Decaying
Convective Weather Patterns			

Experiment Design



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Participants



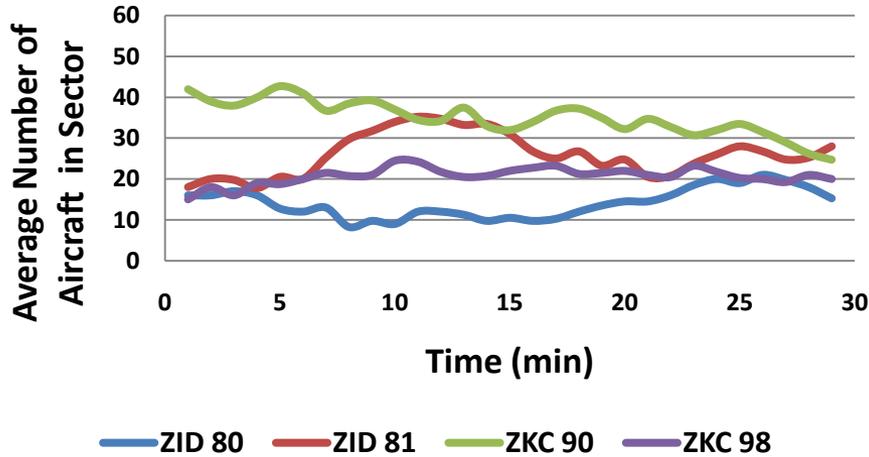
- Six FAA front line managers staffed radar and area supervisor test positions. They were from different en route centers and current on radar
- Four recently retired confederate controllers staffed remaining radar test sector positions
- Four retired confederate “ghost” controllers controlled traffic outside of test area
- Ten general aviation pilots served as pseudopilots for aircraft in the test scenarios

Air Traffic

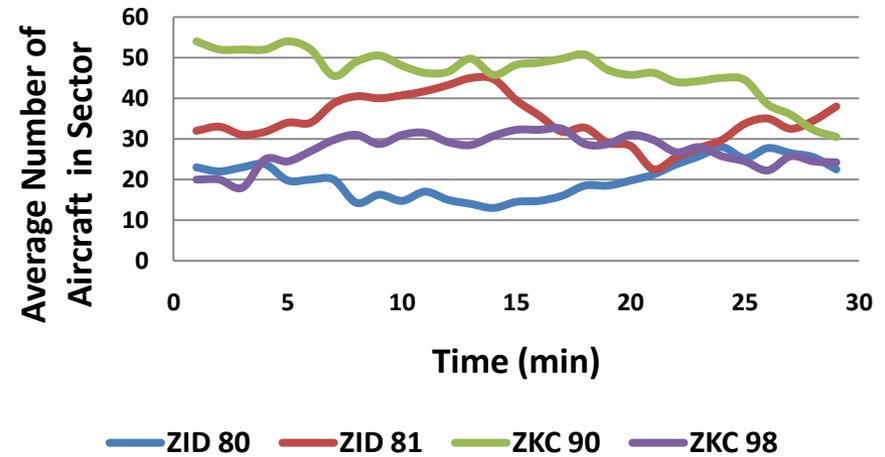


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NextGen Level A



NextGen Level B



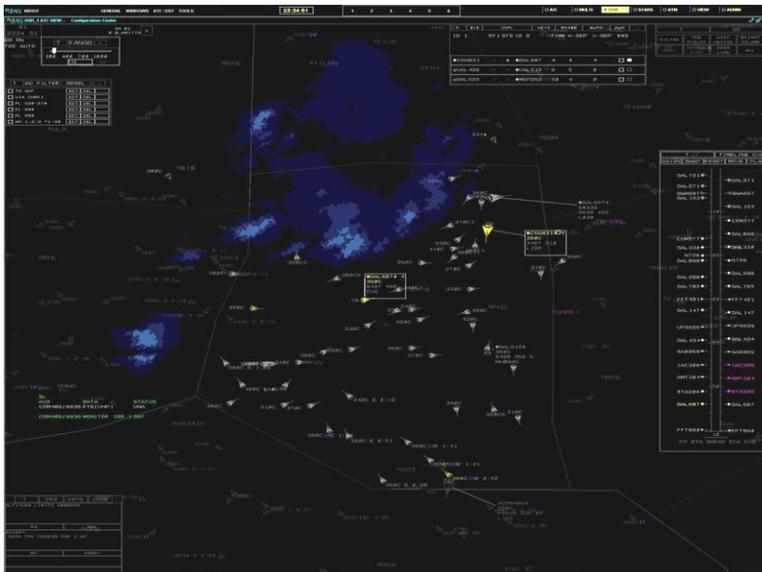
Traffic level	Forecast for year	Test airspace capacity		Aircraft in ZKC-90	
		Number of aircraft	% of 2010 value	Number mean/peak	% of 2010 value
	2010	108	100%	15 / 18	100%
NextGen A	2025	162	150%	35 / 42	233%
NextGen B	2030+	216	200%	46 / 54	300%



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SA Functional Allocation

Automation	Controller
Detect Separation Conflicts	Supervise the automation
Resolve trajectory-based conflicts (if within tolerances)	Resolve trajectory conflicts flagged by the automation
Resolve all time-critical traffic conflicts	Monitor and maintain schedule compliance
Alert controller to urgent problems	Place aircraft back on trajectory following automated tactical maneuvers
Provide trajectory planning assistance	
Use data comm to communicate	

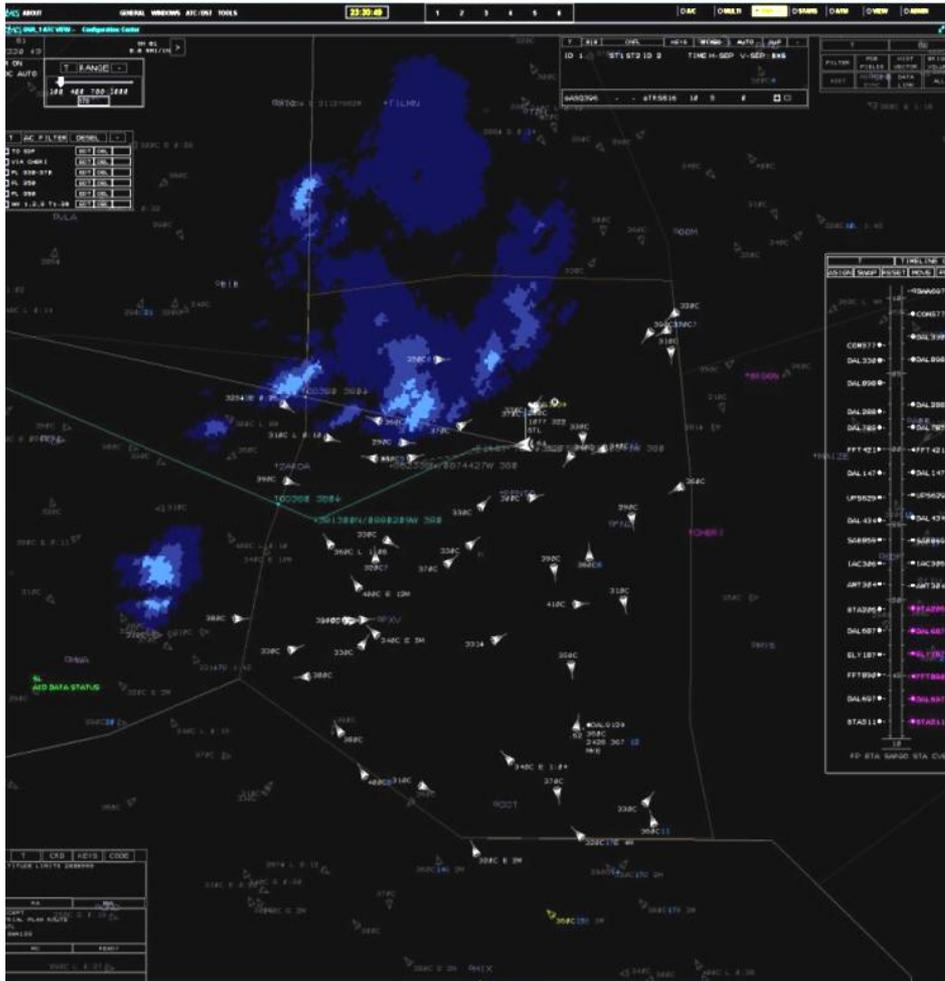


ENRI International Workshop on ATM/CNS
Tokyo, Japan November 10-12, 2010

Apparatus



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- MACS simulation platform
- Advanced controller displays
- 71 cm Barco displays
- DSR keyboards and trackballs
- Voice Switching and Comm. System (VSCS) emulation
- Wall projections of current and predicted traffic situations

Procedure



- Two week study
 - *Three days training*
 - *Five days data collection*
- 30-minute runs
- Participants divided into two teams
- Runs conducted simultaneously in two parallel “worlds”
- ZKC and ZID sectors divided within each world to ensure inter-facility coordination
- FAA test participants rotated through supervisor and radar positions for different perspectives

Results

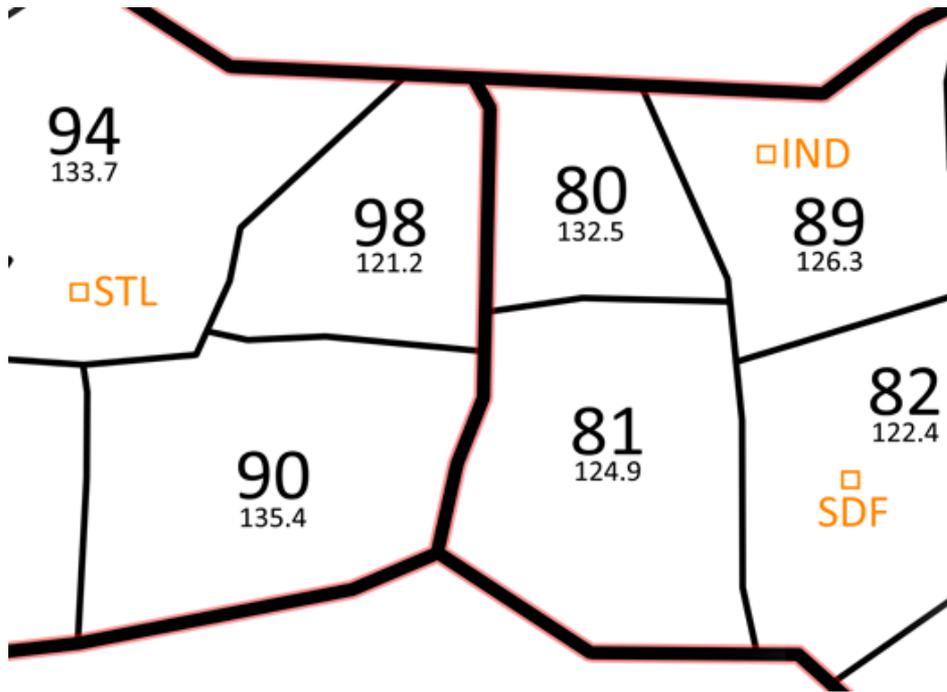


- Airspace and traffic
- Workload
- Conflict detections and resolutions
- Losses of separation
- Subjective participant feedback

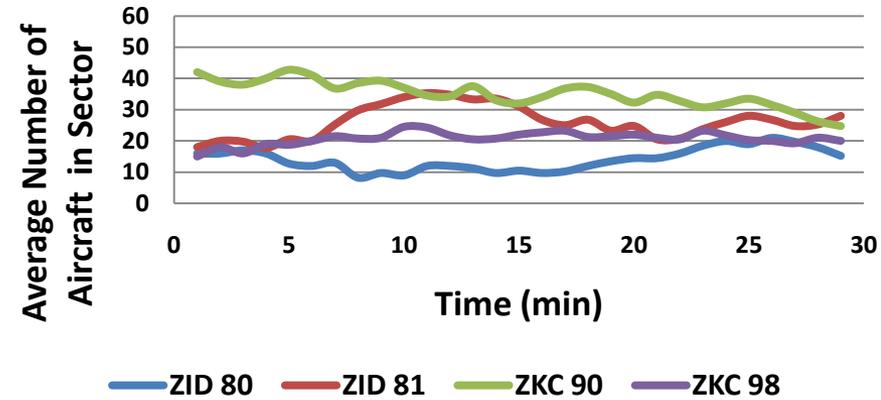
Airspace and Traffic



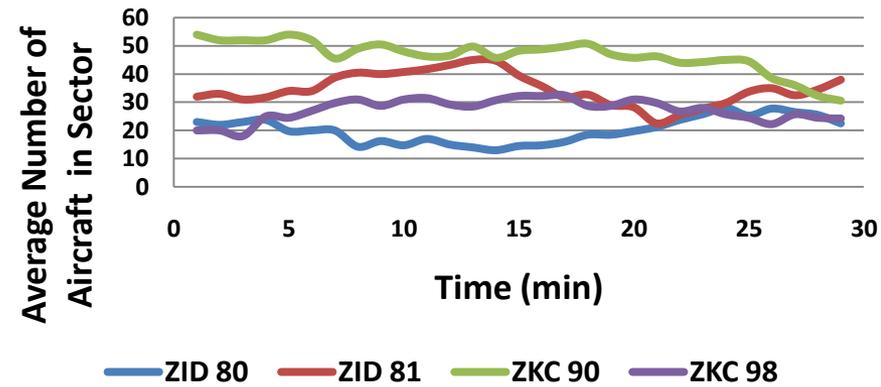
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NextGen Level A



NextGen Level B

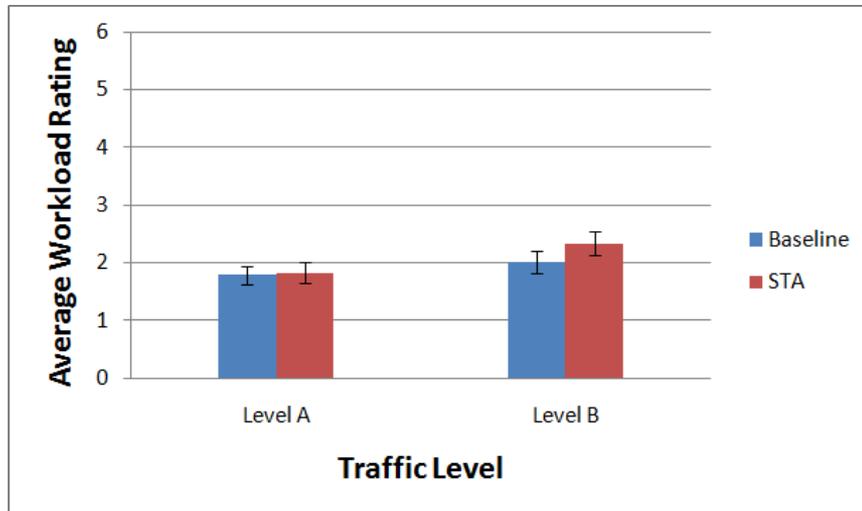


Workload

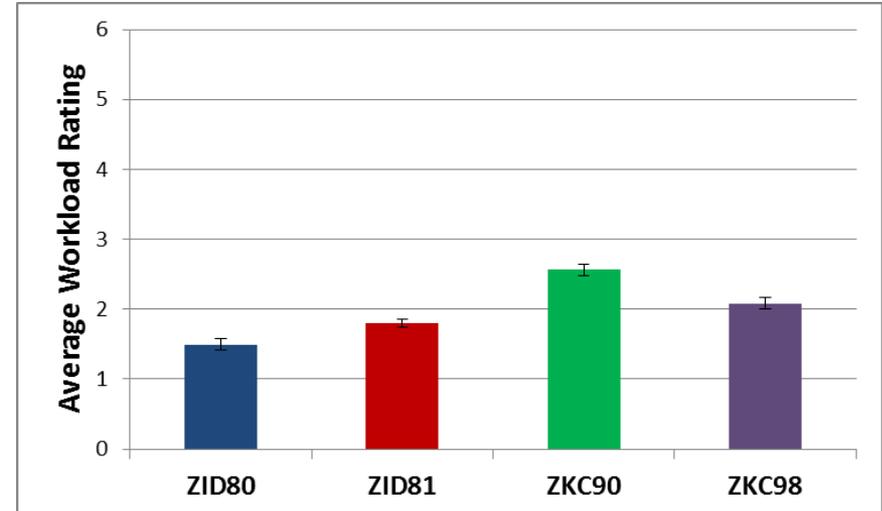


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Workload by condition

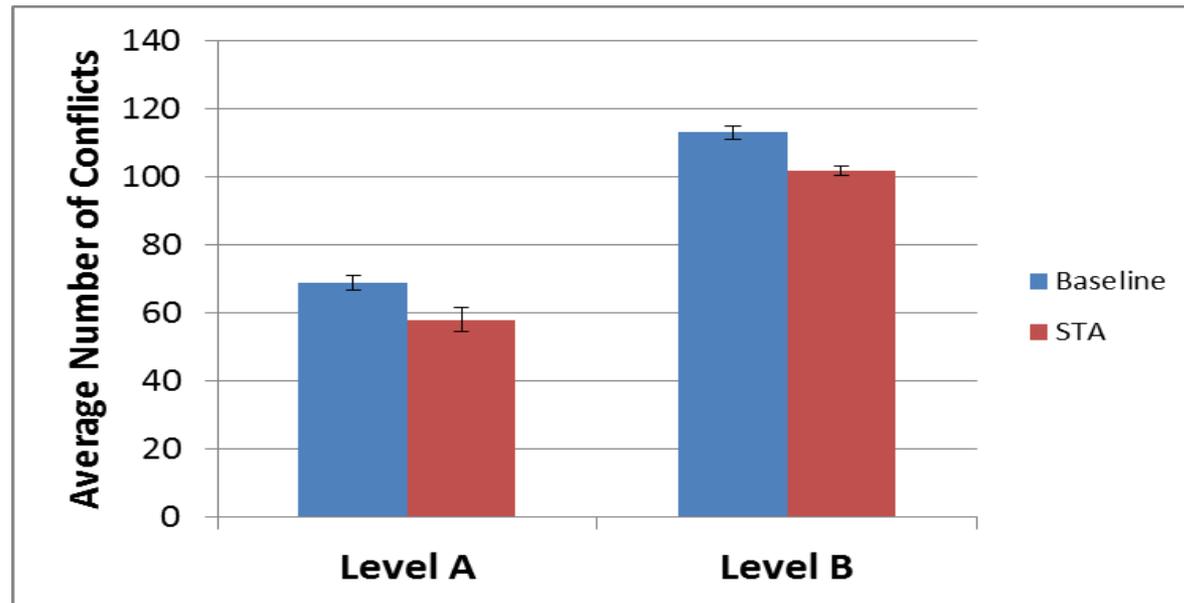


Workload by sector



- Workload significantly higher at Traffic Level B than Level A
- Scheduling constraints did not have an effect on workload
- ZKC90 had significantly higher workload than ZID80 and ZID81 **but not ZKC98**

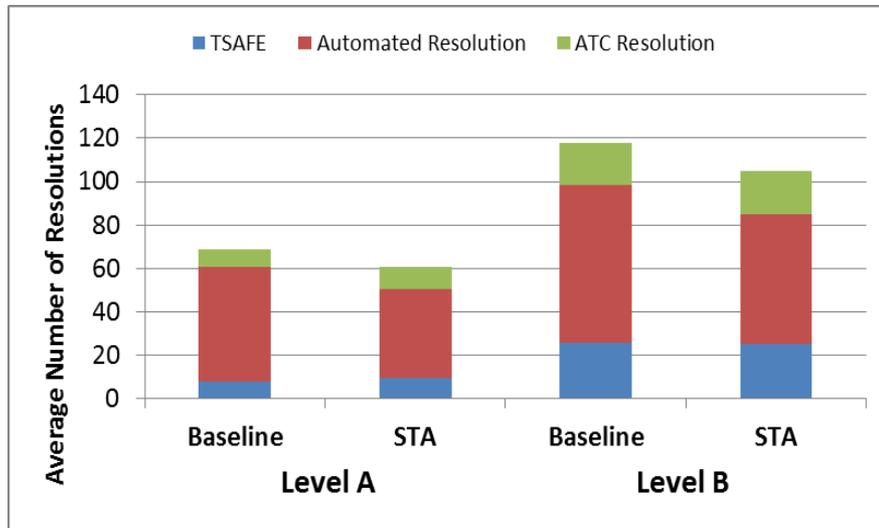
Conflicts: Detections



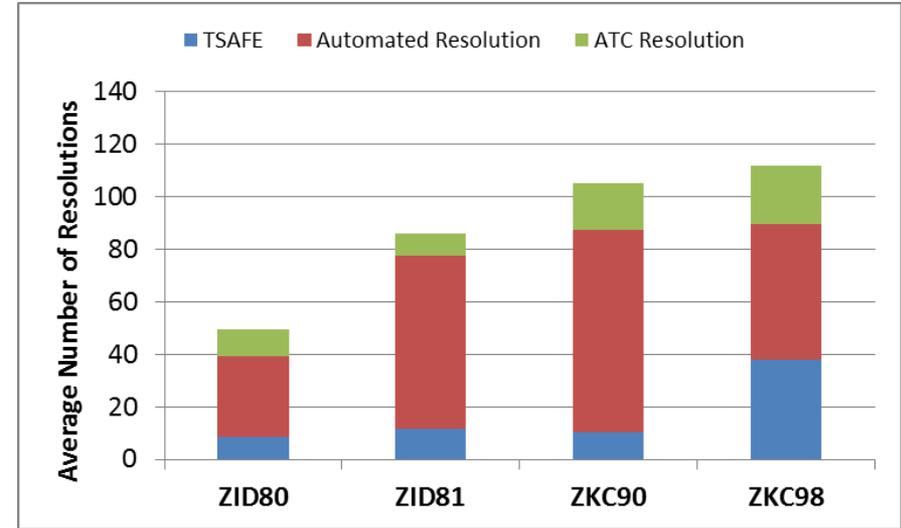
- Traffic Level B had significantly more conflicts predicted to lose separation in the test airspace than Level A
- STA scheduling condition had significantly fewer conflicts than the Baseline condition without scheduling constraints

Conflicts: Resolutions

Resolutions by condition



Resolutions by sector

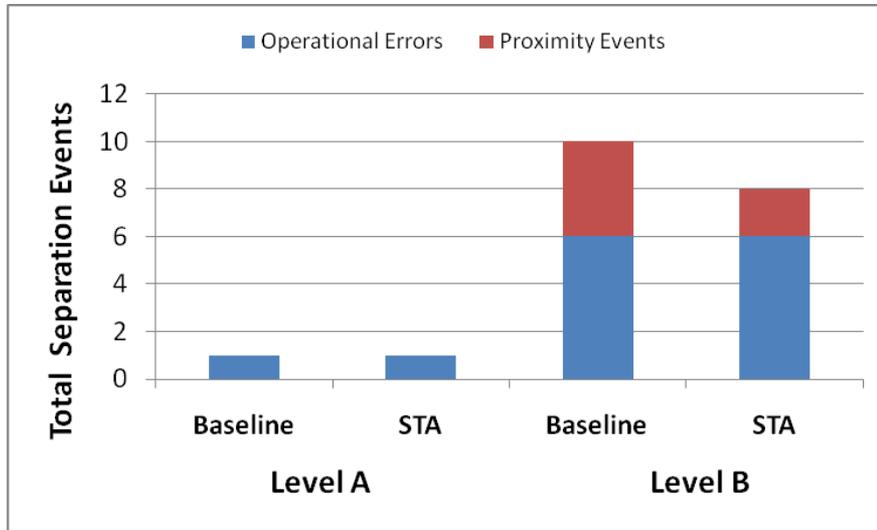


- Majority of conflicts resolved by automation
- ATC involved resolutions increased with traffic levels
- TSAFE events increased with traffic levels
- ZKC98 required the greatest number of conflict resolutions issued
- ZKC98 required greater ATC involved resolutions and TSAFE clearances

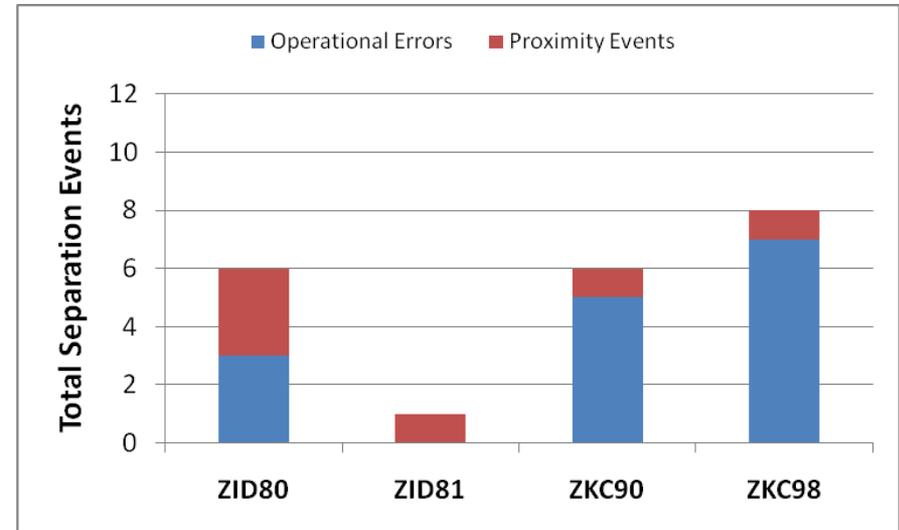


Losses of Separation

Events by condition



Events by sector



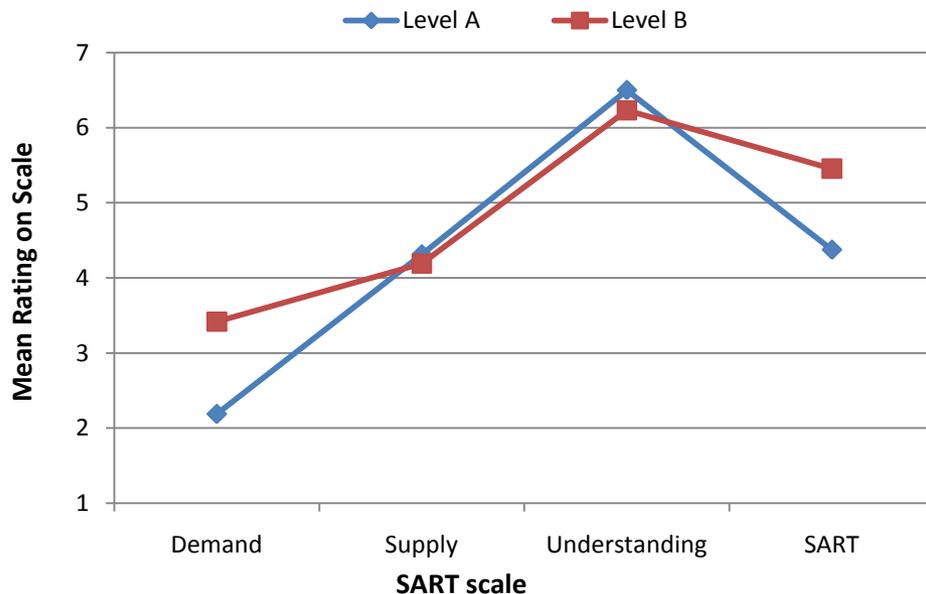
- Traffic Level B resulted in greater numbers of separation events
- Baseline and STA conditions resulted in equal numbers of operational errors
- Baseline had overall greater number of separation events
- ZKC98 had the greatest number of separation events followed by ZKC90

Subjective Feedback:

Situation Awareness



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Situation Awareness Rating Scale

- Spread of responses both between traffic levels and sectors
- “A little” attention demand
- “Average” supply of attention
- “Very good understanding” of situation
- **“Reasonable situation awareness”**

Subjective Feedback: Acceptability



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- Questions on acceptability of operations aligned with Controller Acceptance Rating Scale (CARS)
- Acceptability of safety in Traffic Level A rated at 90.6% and Traffic Level B at 67.5%
- Volume of traffic not a concern but the greater complexity of the traffic and fewer resolution options were

Subjective Feedback: Impressions



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- “...it seemed as if controller and automation fought against each other at times to resolve conflicts.”
- “it seems fairly natural, why not do it?”
- “You’re on the right track.”
- **“It’s inevitable, I think the concept is strong, it needs work and testing, I think it’s the way we’re going to go.”**

Summary



- Increase from Traffic Level A to B provided the most noteworthy results
- Mean workload, conflicts detected, and losses of separation counts were all higher in Level B
- “Reasonable situation awareness” was maintained at both traffic levels but Level B was rated as less safe (CARS) and more attention-demanding (SART) than A
- At the sector level, local complexity more of an issue than simple aircraft count (e.g., ZKC98)

Conclusion

- The functional allocation of separation assurance between controller and ground-based automation presented was well received and held promising results
- An important component to being able to accommodate the envisioned future demand is the appropriate identification and handling of local complexities

Questions?