Analytical results of ionospheric delay gradient based on GPS monitoring stations near Suvarnabhumi airport in Thailand

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Outline

- Introduction
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Ionospheric effects on GNSS signals





 $\delta t = t_{s*} - t_s = \frac{40.3}{cf^2} \int_{s*} N_e ds$ (second)

Ionospheric delay $I = c \times \delta t = \frac{40.3}{f^2} TEC \quad (meter)$

- $\boldsymbol{t}_{\boldsymbol{s^*}}$: Traveling time with an ionosphere
- $\mathbf{t}_{\mathbf{s}}$: Traveling time without an ionosphere



- The ionospheric irregularities cause the fluctuations in the refractive index (n).
- It causes the rapid fluctuations in amplitude and phase of GNSS signals.
- In the worst case, the receiver loss of lock the satellite signal.

Ionospheric effects to GBAS

GBAS (Ground-Based Augmentation System)



• The reference stations provide the differential corrections to the receiver that are equipped in the aircraft in the nearby area.

• However, the ionospheric irregularities cause the error of the differential correction information that broadcast to the aircraft.

• For the GAST-D (GBAS Approach Service Type D), the error of differential corrections shall be less than 1.5 m within 5 km of the runway threshold (300 mm/km).

Ionospheric effects to GBAS

20 November 2003



The extreme ionospheric delay gradient observed in US.

S. Datta-Barua, et al., 2010.

Ionospheric effects to GBAS



• Here, we focus on the Front Slope or "Ionospheric delay gradient".

• Ionospheric delay gradient problems

1. Due to the physical ionospheric separation between aircraft and reference station.

2. Due to the ionospheric irregularities (plasma bubbles, SED).

• Q : How large of the ionospheric delay gradient in the low latitude regions can be?

In this study, we focus on the ionospheric delay gradient associated with plasma bubbles in Thailand, which is located in low-latitude region

How to derive TEC from GPS data?



- Since the STEC_P is nosier than STEC_L but the STEC_L still has an initial ambiguity which frequently causes the STEC_L to have negative values.
- Generally, STEC_L is adjusted to STEC_P level.

$$STEC_{adj} = STEC + B_{S} + B_{R}$$

 For dual-frequencies GPS receiver, the Slant TEC can be derived by both psedorange and carrier phase linear combinations.

Pseudorange :	$STEC_{P} = k(P_2 - P_1)$
Carrier phase :	$STEC_{L} = k(L_1 - L_2)$

where k=9.5196 for TEC expressed in TECU.



Receiver bias calibration

Single difference method 1 September 2011 STEC 40 KMITL **GPS** satellite 30 STFD STEC (TECU) 20 10 0 -10 -20 ^L_____ 10 13.5 10.5 12 12.5 11 11.5 13 14 14.5 15 Ionosphere dSTEC STEC₄k STEC,^k 10 Ionospheric **Quiet time** dSTEC (TECU) 8 disturbance d Br_{STFD}-Br_{KMITL} 6 Station 2 Station 1 4 $STEC_{adj-1}^{k} = STEC_{1}^{k} + B_{S}^{K} + B_{R-1}$ 2 L 10 10.5 11 11.5 12 12.5 13 13.5 14.5 14 15 $STEC_{adi 2}^{k} = STEC_{2}^{k} + B_{S}^{K} + B_{R 2}$ Time (UTC) (STEC_{STED}-STEC_{KMITL}) + (Br_{KMITL}-Br_{STFD})

$$dSTEC^{k} = STEC_{adj_{1}}^{k} - STEC_{adj_{2}}^{k}$$
$$= (STEC_{1}^{k} - STEC_{2}^{k}) + (B_{R1} - B_{R2})$$

Short baseline experiments



• Short baseline experiment needs to be carried out to monitor the ionospheric delay gradients near Suvarnabhumi international airport.

• Three dual-frequency GPS receivers have been installed as part of a cooperation project of

- 1. King Mongkut's Institute of Technology Ladkrabang (KMITL)
- 2. Electronic Navigation Research Institute (ENRI), Japan
- 3. Aeronautical Radio of Thailand Ltd. (AEROTHAI)
- 4. Stamford International University
- This project started July 2011.









Short baseline experiments



Ionospheric delay gradient (mm/km)

Lam

Plathew

ลำปลาทิว

KMIT

4 km

Sisa

Cho

ศรีษะ

Chorakhe

ศรีษะจรเข้

Lat k

AERO

Nong Prue

หนองปรือ

ท่าอากาศยาน ສວງວານທຸມ

คลองสาม

ประเวศ

12 km

Racha

ROTI (Rate of TEC change index)



• In order to check the ionospheric irregularities, we use the rate of TEC change index or ROTI to indicate whether the plasma bubbles occur or not.

$$ROT(i) = STEC(i+1) - STEC(i)$$

$$ROTI = \sqrt{\frac{1}{N} \sum_{i=1}^{N} (ROT(i) - \overline{ROT})^2}$$

• The ROTI is defined by Standard deviation of rate of TEC change with 5-minute window.

ROTI (Rate of TEC change index)





1st September 2011



• In the results, we selected the data on 1 September 2011 to analyze.

• The constant level can be considered as the differential receiver biases.

PRN2, 9, 14, 21, 29

1st September 2011



• However, we found a slight offset exist in AERO-KMIT direction due to the uncertainty offset in the adjustment step (L. Ciraolo, et al., 2007).

• Therefore, we consider the differential receiver biases for each satellite.

L. Ciraolo, et al., 2007.

PRN2, 9, 14, 21, 29

1st September 2011



PRN2, 9, 14, 21, 29

22nd September 2011



Conclusions

- From this study, we show the ionospheric delay gradients near Suvarnabhumi airport, Thailand, in September equinox 2011.
- Based on 15-day observation, we found that the maximum ionospheric delay gradient can reach 192.36 mm/km on 22nd September 2011.
- For the GBAS implementation in this area, the local ionospheric threat model should consider the maximum ionospheric delay gradient.

Thank you for your attention! Question?