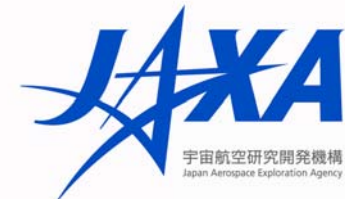


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# Development of an Onboard Doppler LIDAR for Flight Safety

Hamaki Inokuchi and Hisamichi Tanaka  
(Japan Aerospace Exploration Agency)

Toshiyuki Ando  
(Mitsubishi Electric Corporation)



# Contents

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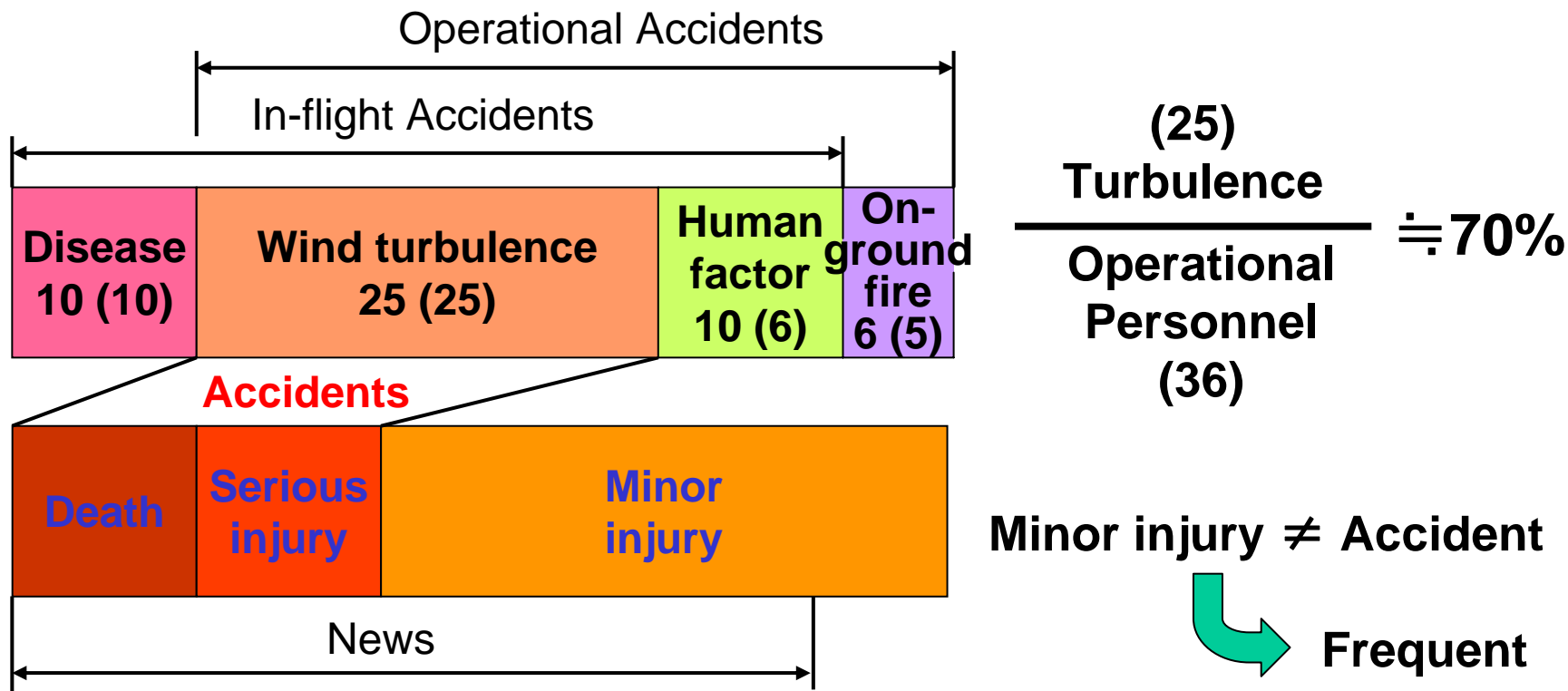
- Aviation Accidents
- Onboard Doppler LIDAR
- 1NM Model
- 3NM Model
- 5NM Model
- Plans for the Near Future
- Summary

1NM = 1852 m

# Aviation Accidents

Large civil airplane in Japan (1990~2006)

(Parentheses are the number of personnel accidents)



# Turbulence Accident Prevention

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## Prior information

- Weather forecast: Invalid for the small area on enroute
- Weather RADAR: Invalid for the clear air turbulence
- Information from precedence: Invalid for the short time change

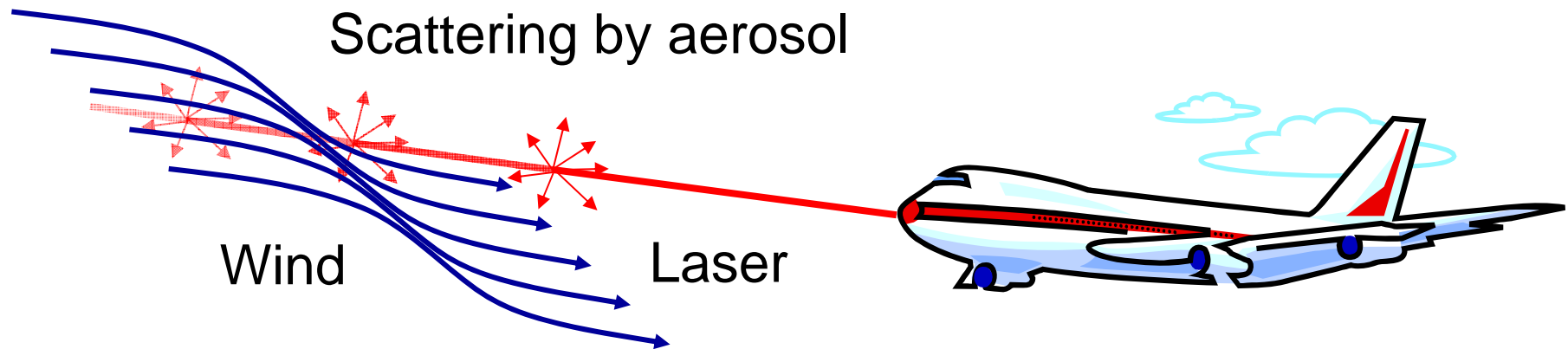
## Damage reduction

- Seat belt: Difficulty in the cabin service
- Gust alleviation: Invalid for the initial shake
- Interruption of the cabin service: Much time is required
- Evasion flight: Prior reliable information is required

If turbulence is predicted beforehand,  
these measures become more effective.

# Onboard Doppler LIDAR

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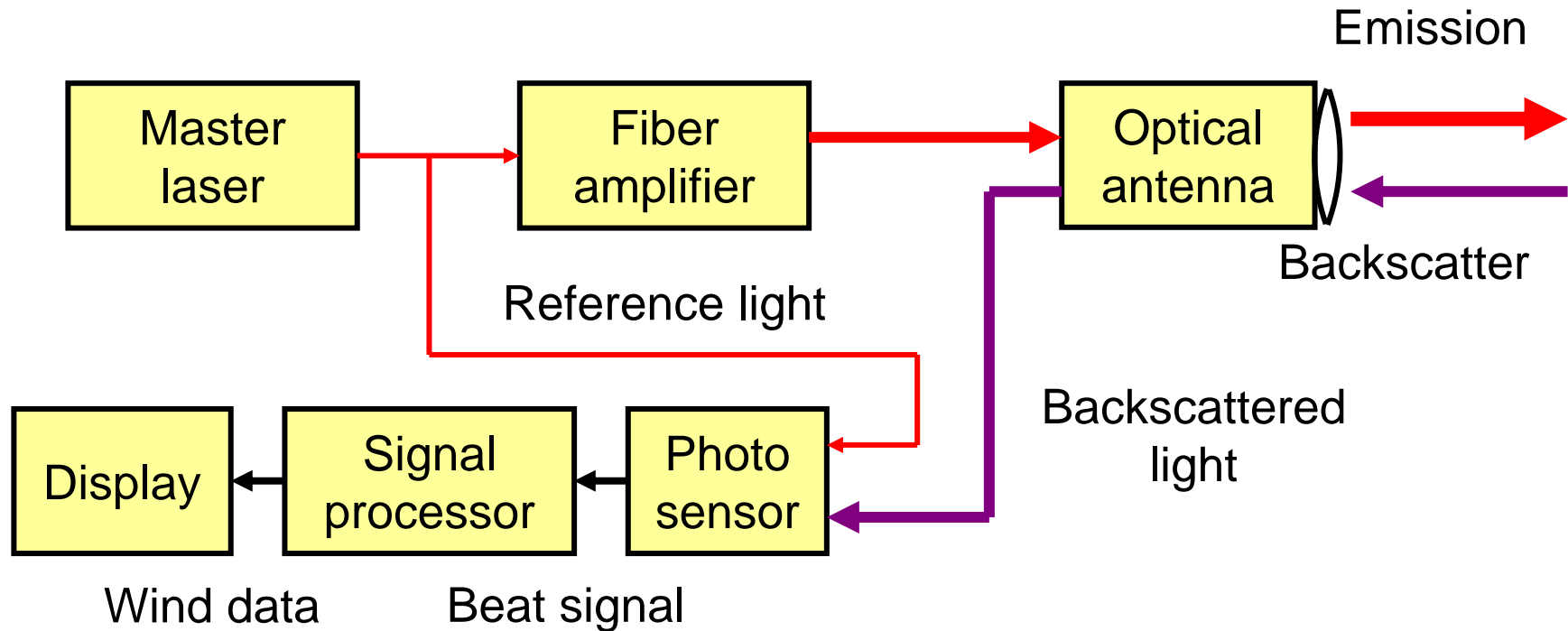


LIDAR: Light Detection And Ranging

Overall Concept of the Onboard Wind Measurement LIDAR

# Onboard Doppler LIDAR

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Block Diagram of Coherent Doppler LIDAR  
Based on Optical Heterodyning Technique

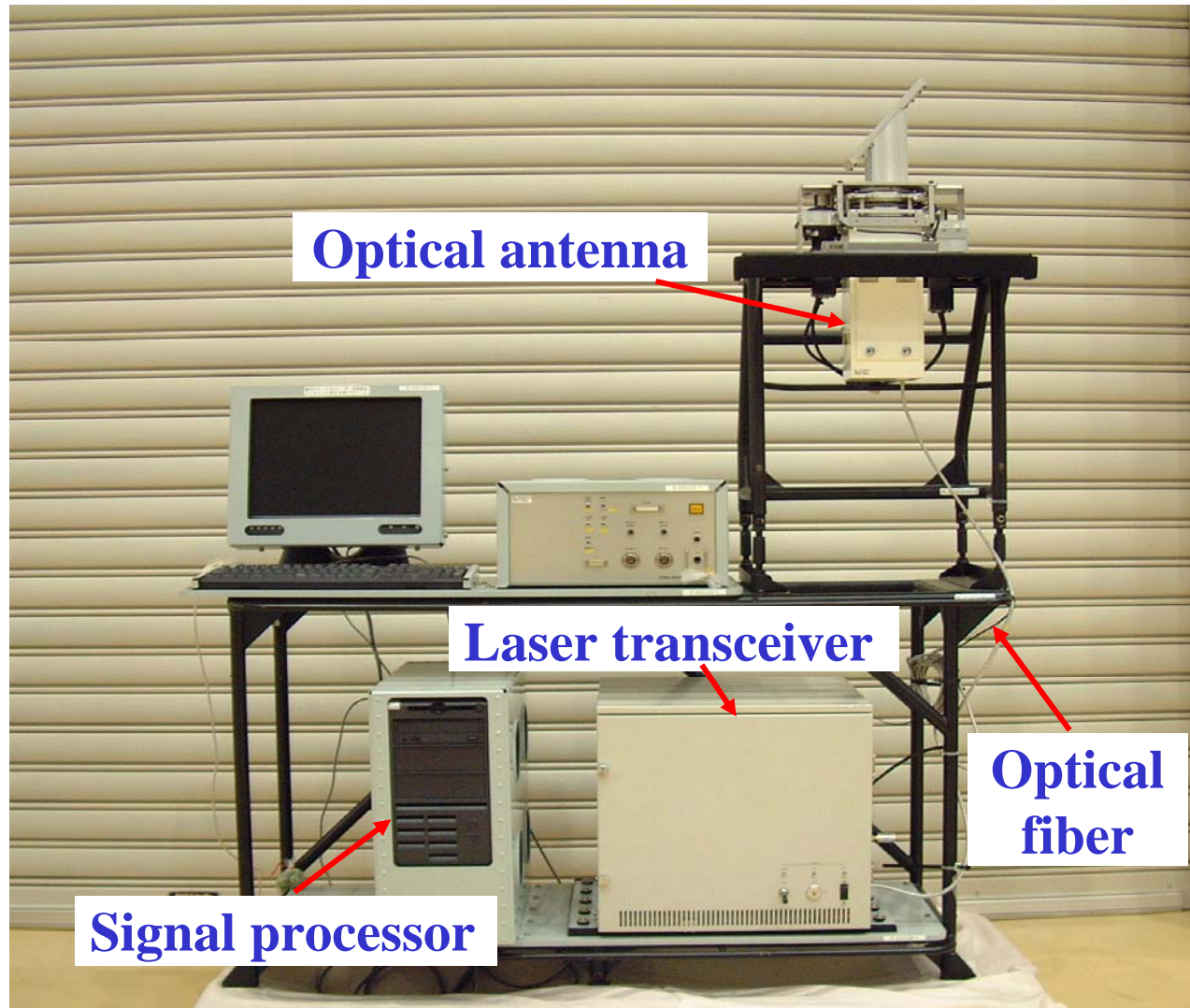
# Adopted Method

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## Optical fiber amplifier

- **Small**: Optical devices are small, power-saving and a huge chiller is unnecessary
- **High reliability**: Dust-proofness and low EM noise
- **Flexible layout**: Separate installation is possible
- **Eye safety**:  $1.5 \mu\text{m}$  is the safest wavelength

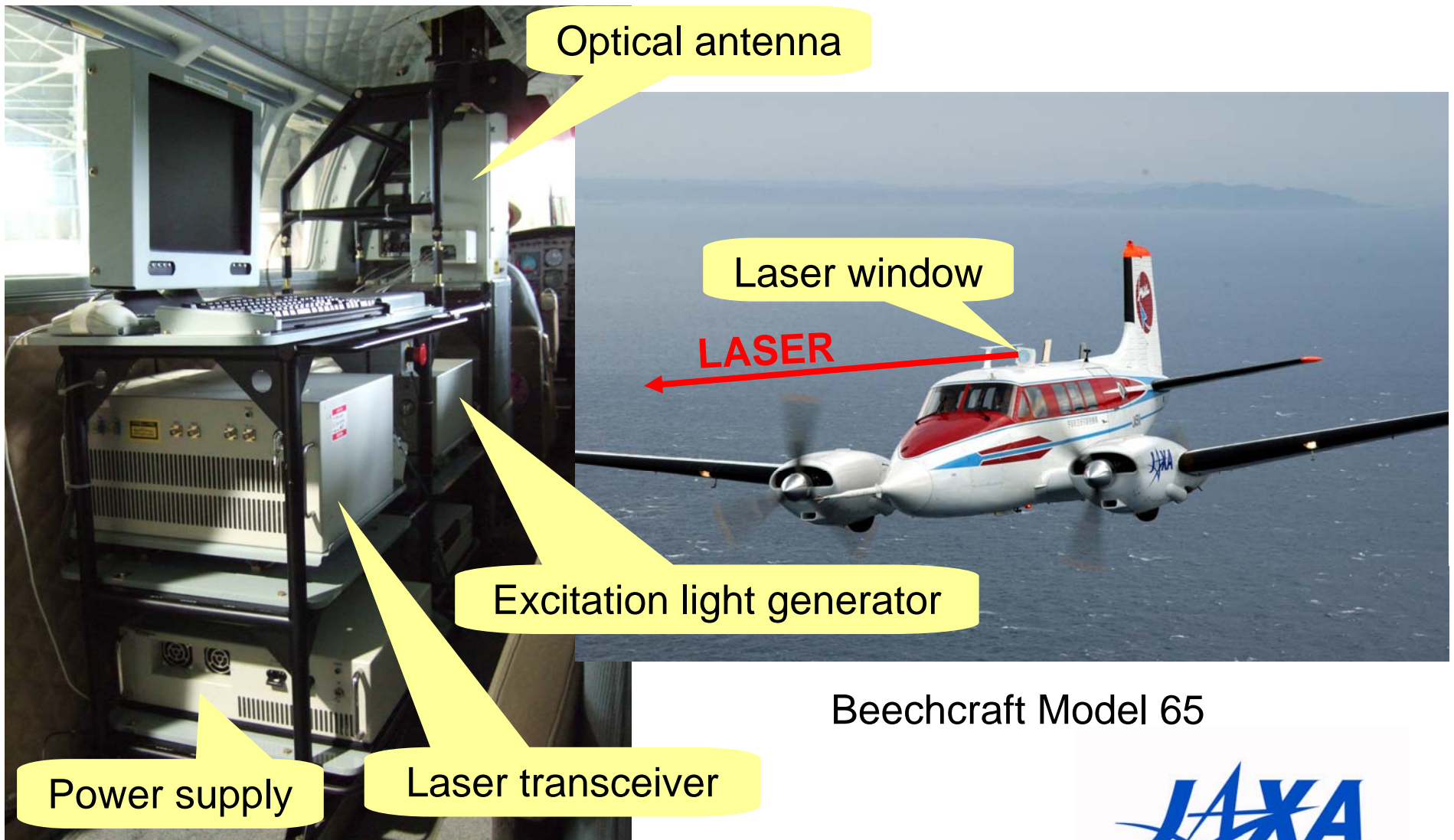
**Suitable as an onboard system**



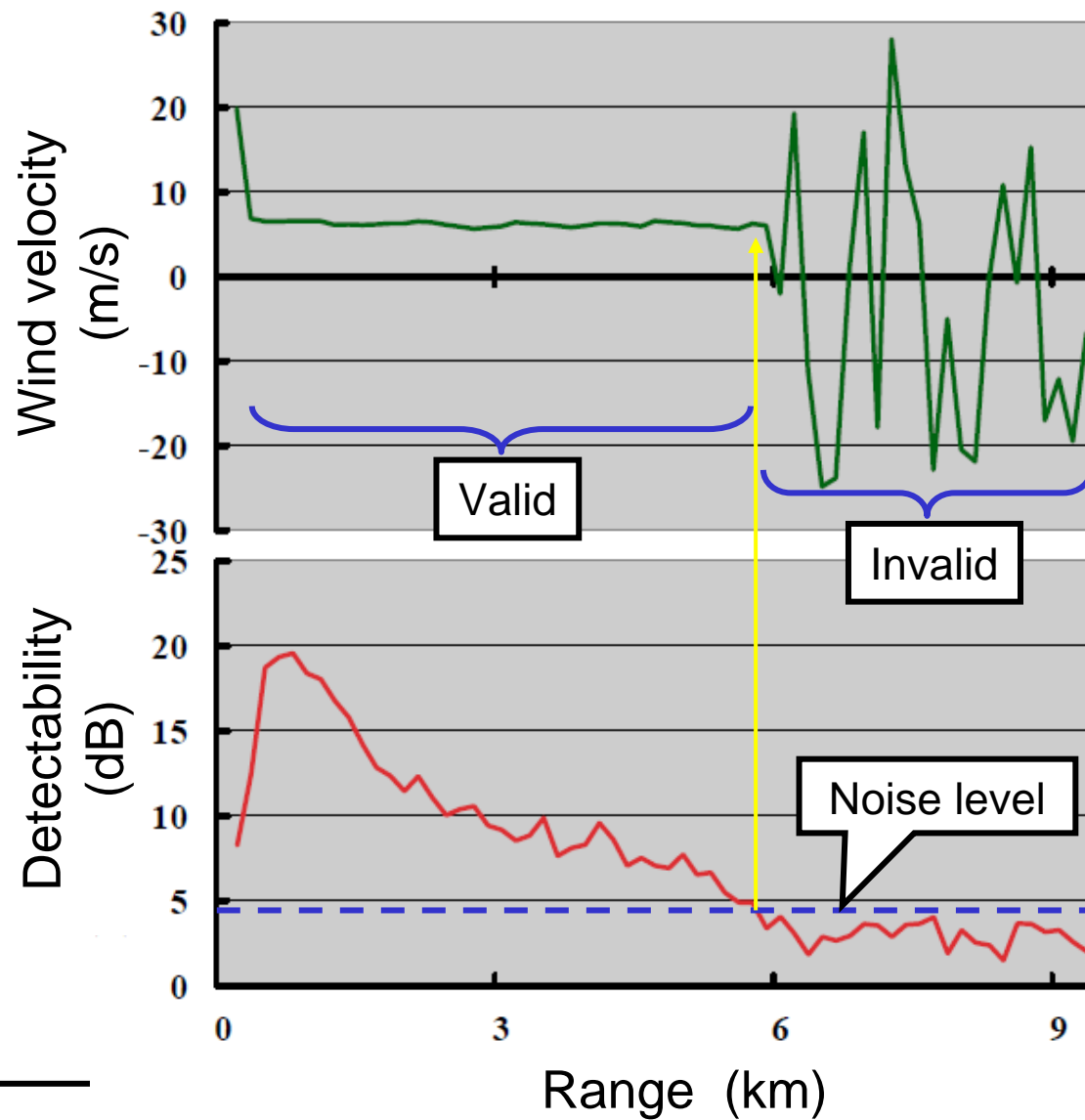


# Installation (3NM Model)

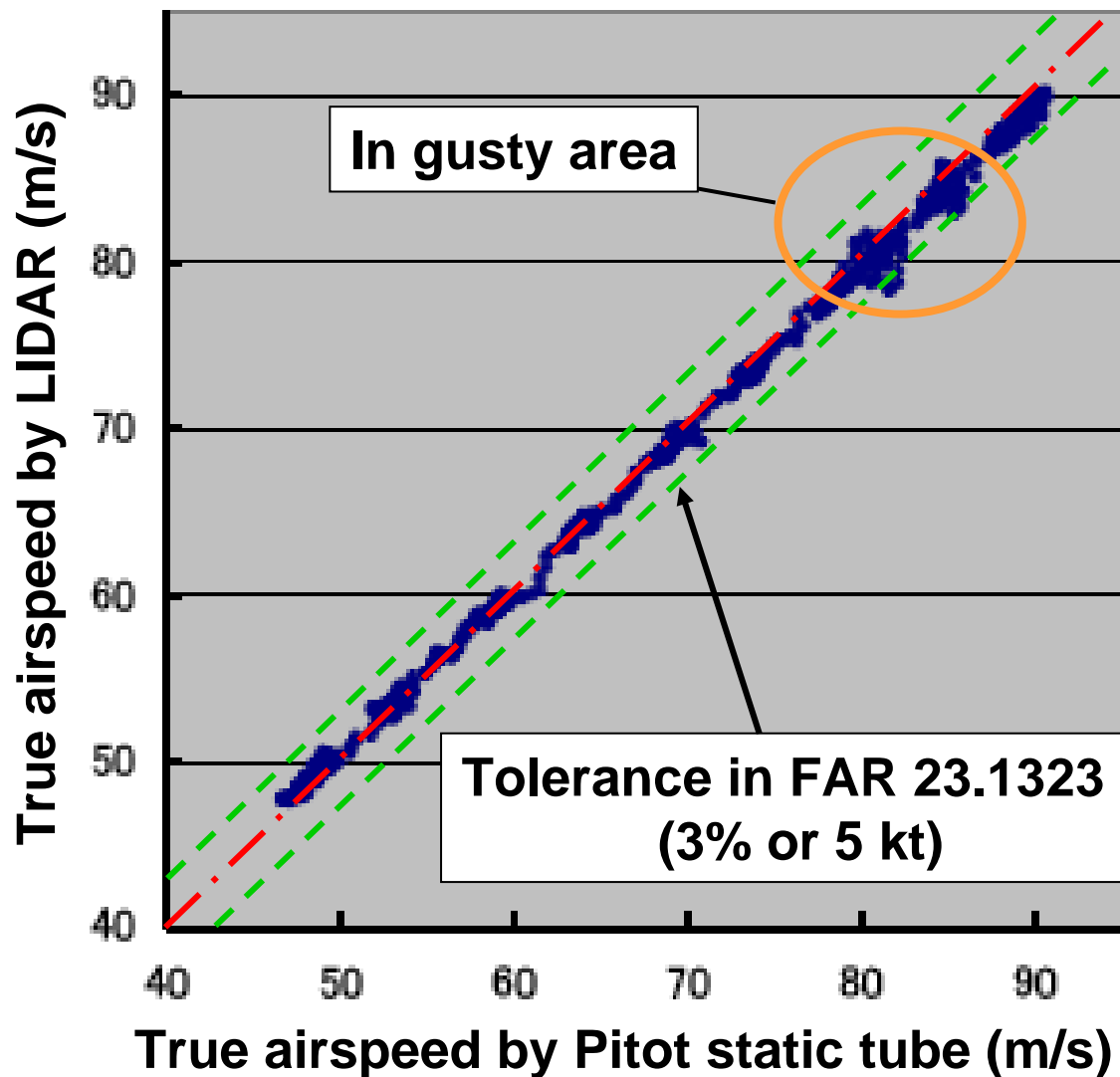
2006



# Flight Test Data (3NM Model)



# Flight Test Data (3NM Model)

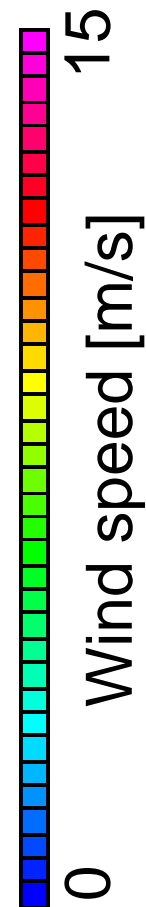


Measured range (m)	Standard deviation (m/s)
450-600	0.63
600-750	0.68
750-900	0.69
900-1050	0.70

**Equivalent accuracy to the Pitot tube**

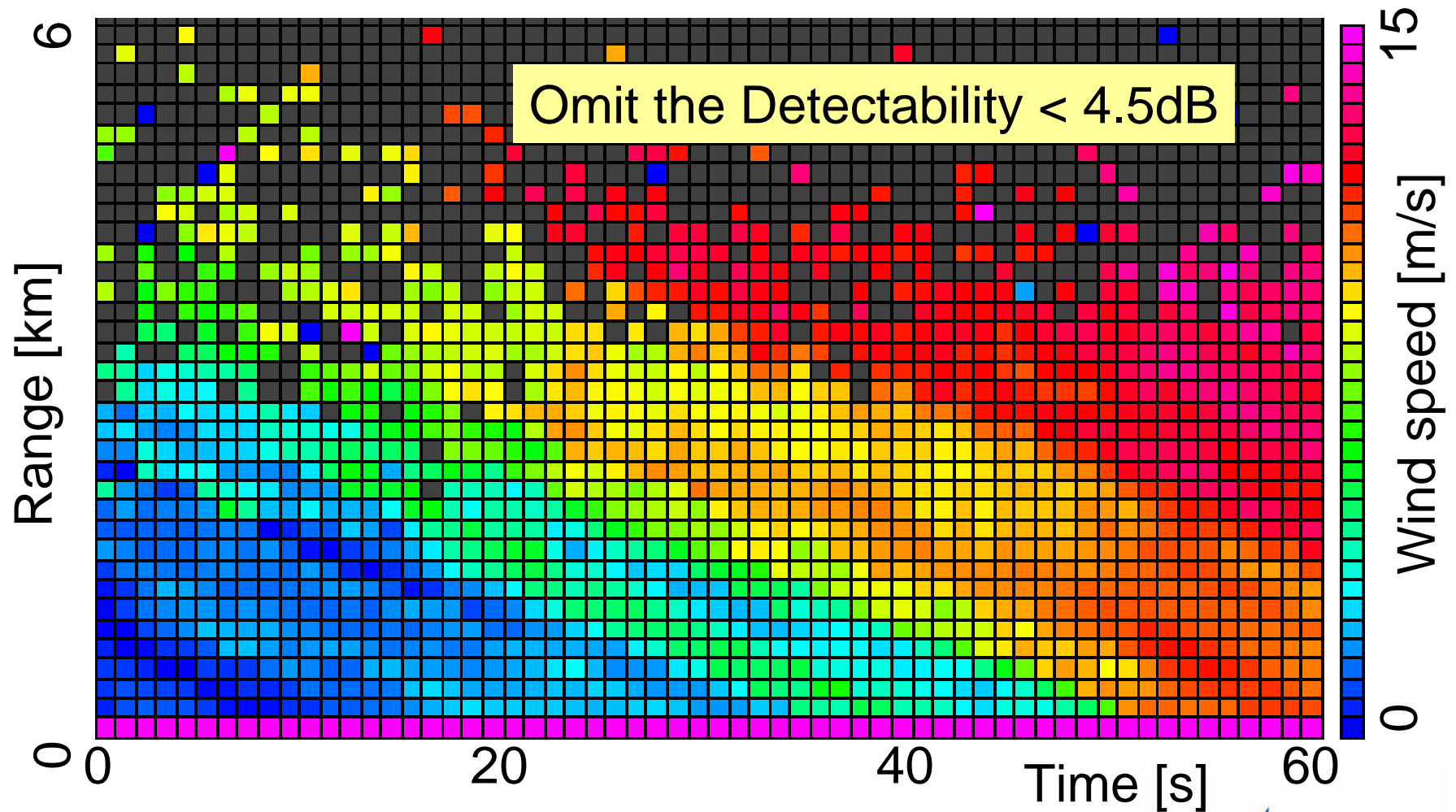
# Flight Test Data (3NM Model)

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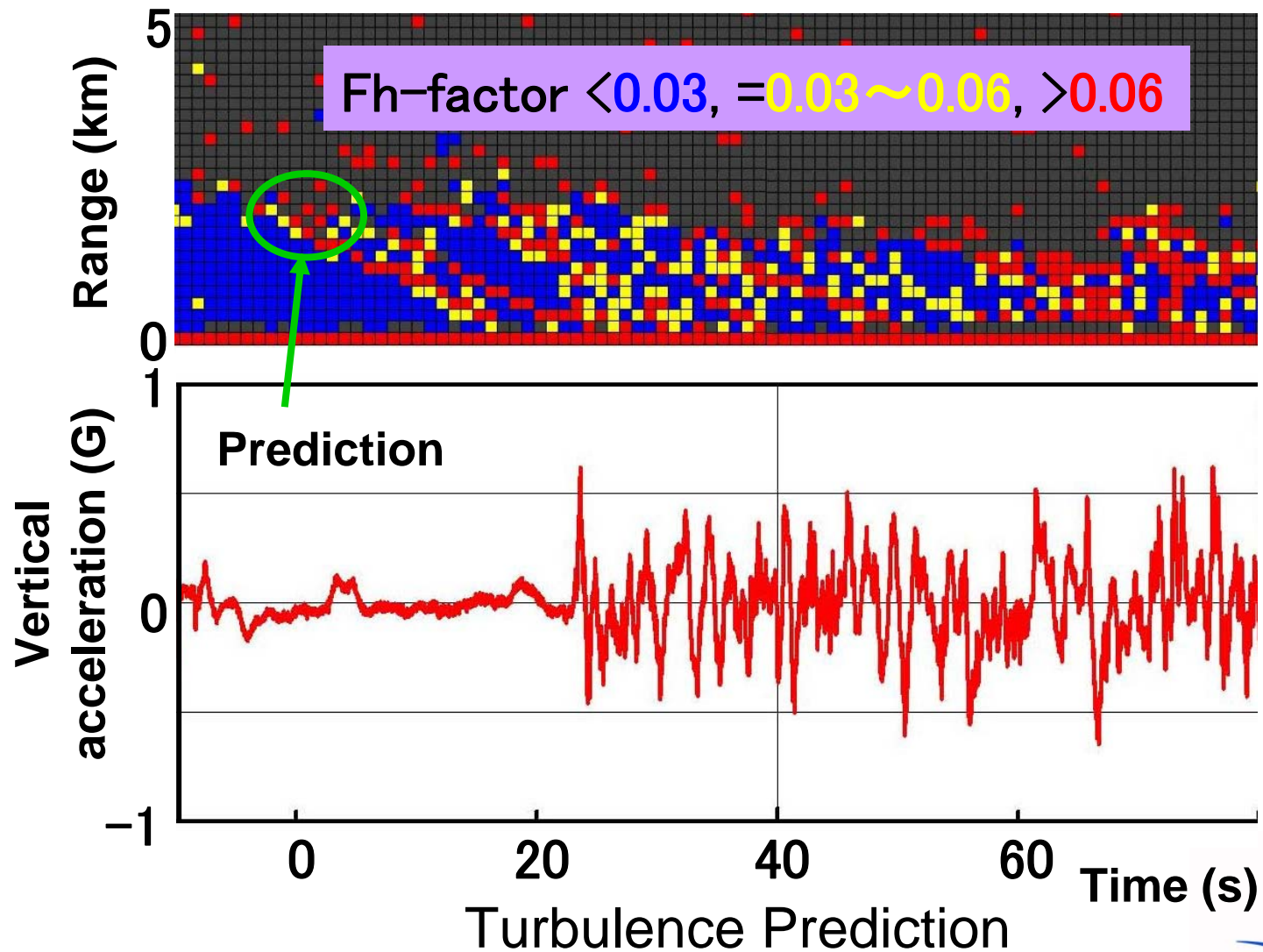
Measured data

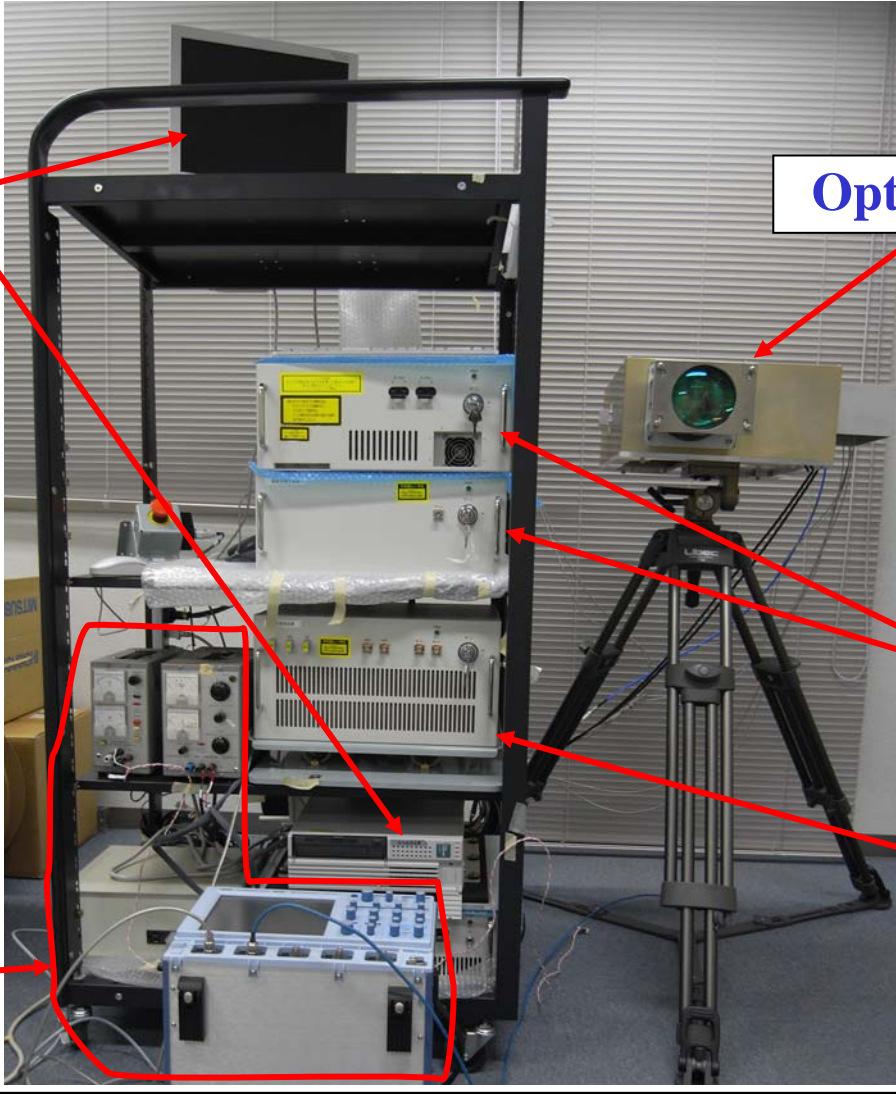
# Flight Test Data (3NM Model)



Cleaned data

# Flight Test Data (3NM Model)





PC

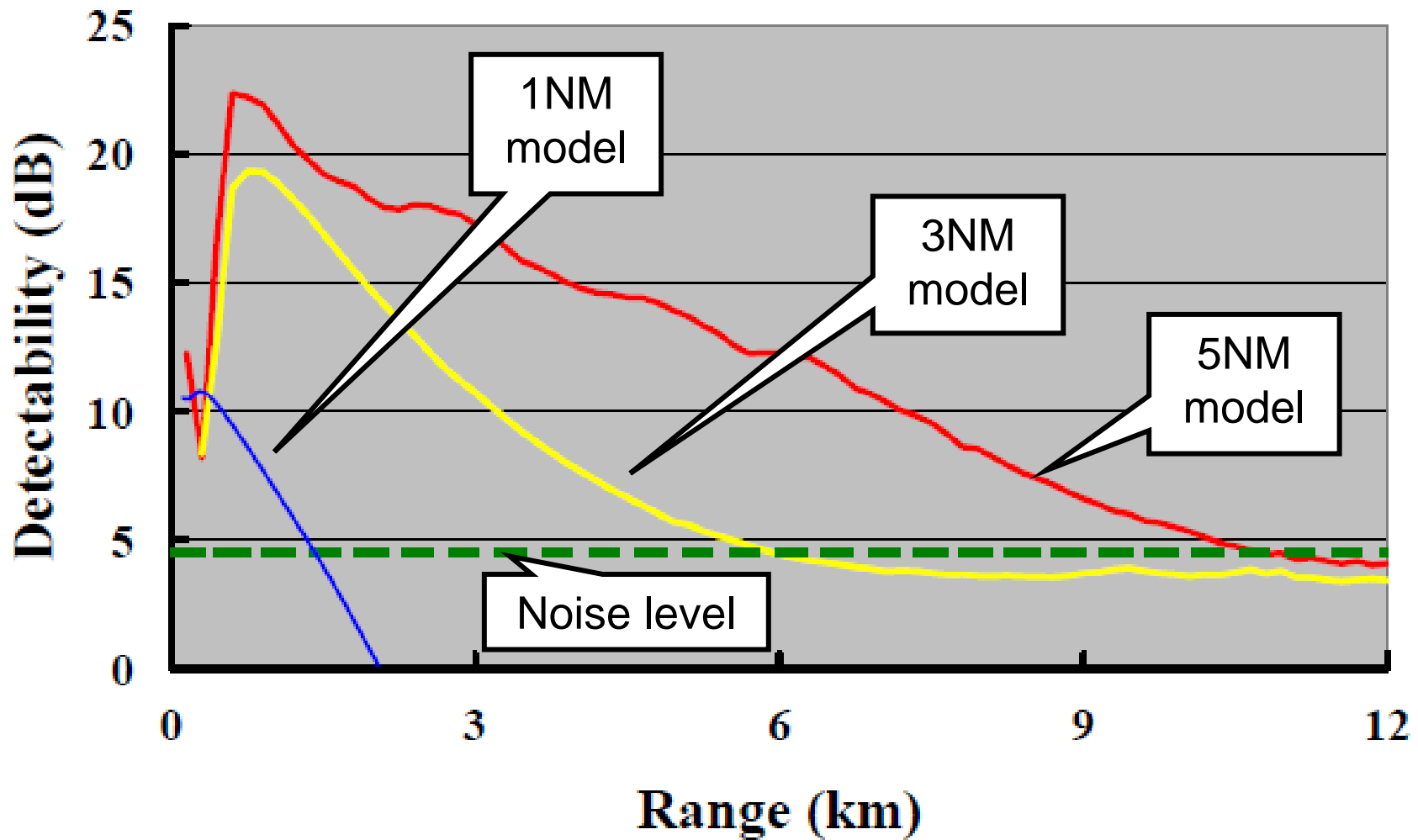
Optical antenna

Excitation  
light generator

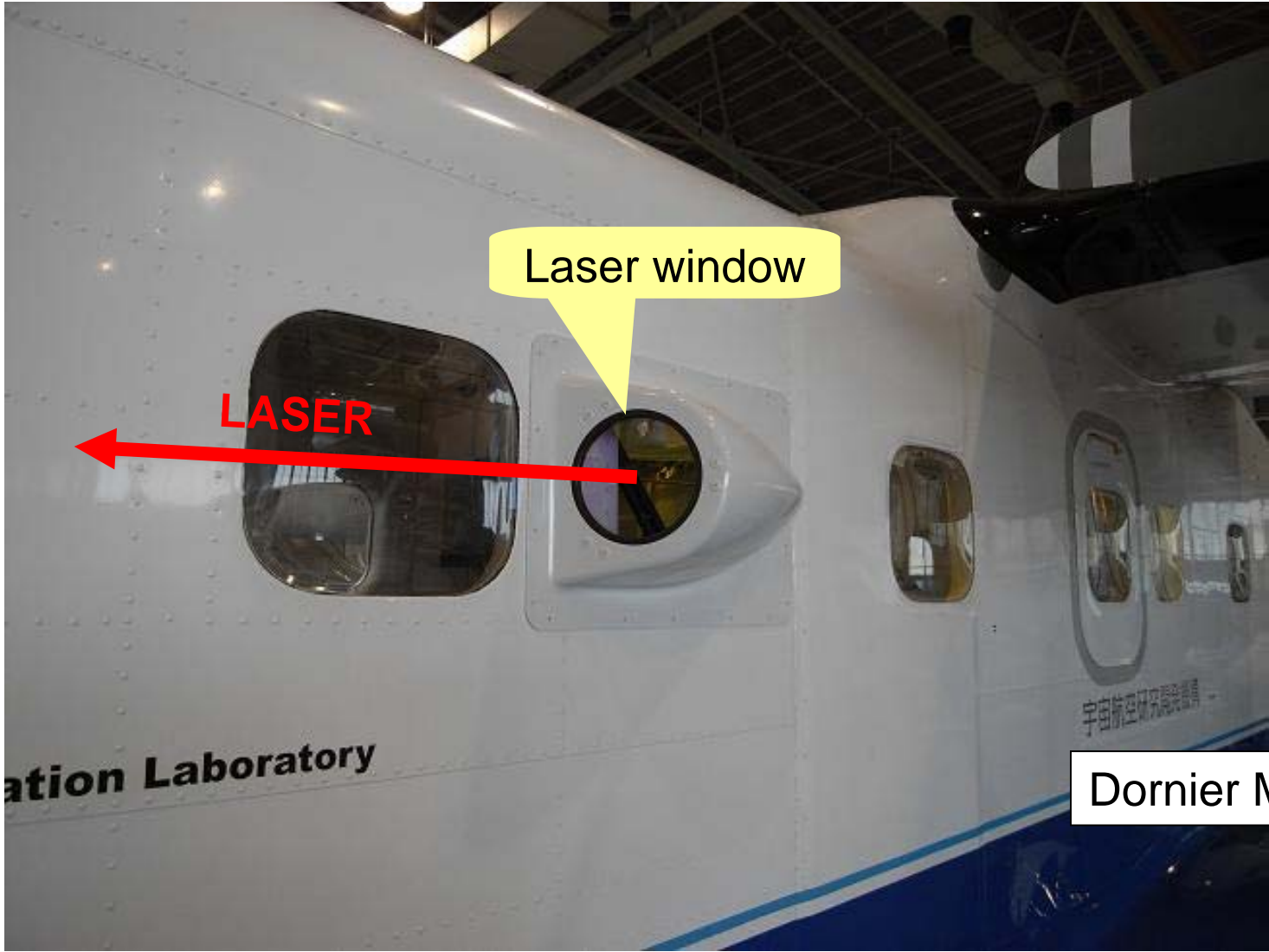
Laser transceiver

Ground test  
equipment

# Ground Test Result







Dornier Model 228

# Specifications

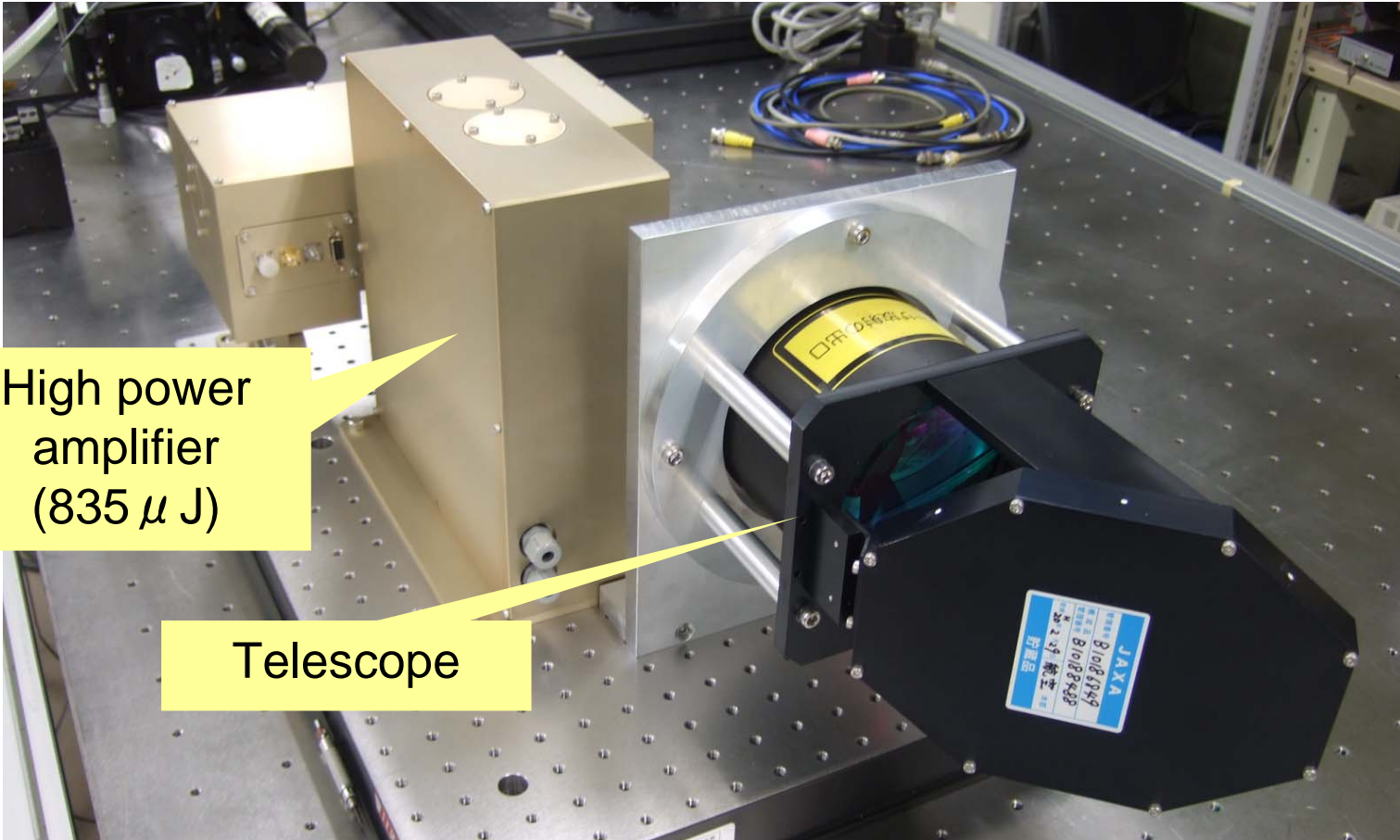
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	1NM model (2001)	3NM model (2006)	5NM model (2007)
Laser peak power	10 W	90 W	323 W
Laser pulse energy	4.5 $\mu$ J	58 $\mu$ J	179 $\mu$ J
Pulse repetition frequency	50 kHz	4 kHz	4 kHz
Aperture diameter	50 mm	110 mm	110 mm
Power consumption	420 W	306 W	374 W
Weight	105 kg	51 kg	82 kg

## Plans for the Near Future

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- Flight demonstration of the 5NM model is planned in March 2009
- Development of a 5NM high altitude model is planned in February 2009
- High altitude demonstration using a jet plane is planned in 2009



High power  
amplifier  
(835  $\mu$  J)

Telescope

Optical antenna

# Summary

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- Turbulence accidents are frequent.
- Range of 3NM was demonstrated in flight.
- LIDAR has sufficient accuracy as a sensor.
- Range of 5NM was demonstrated on ground.
- Development of a high altitude model is planned in FY 2008.